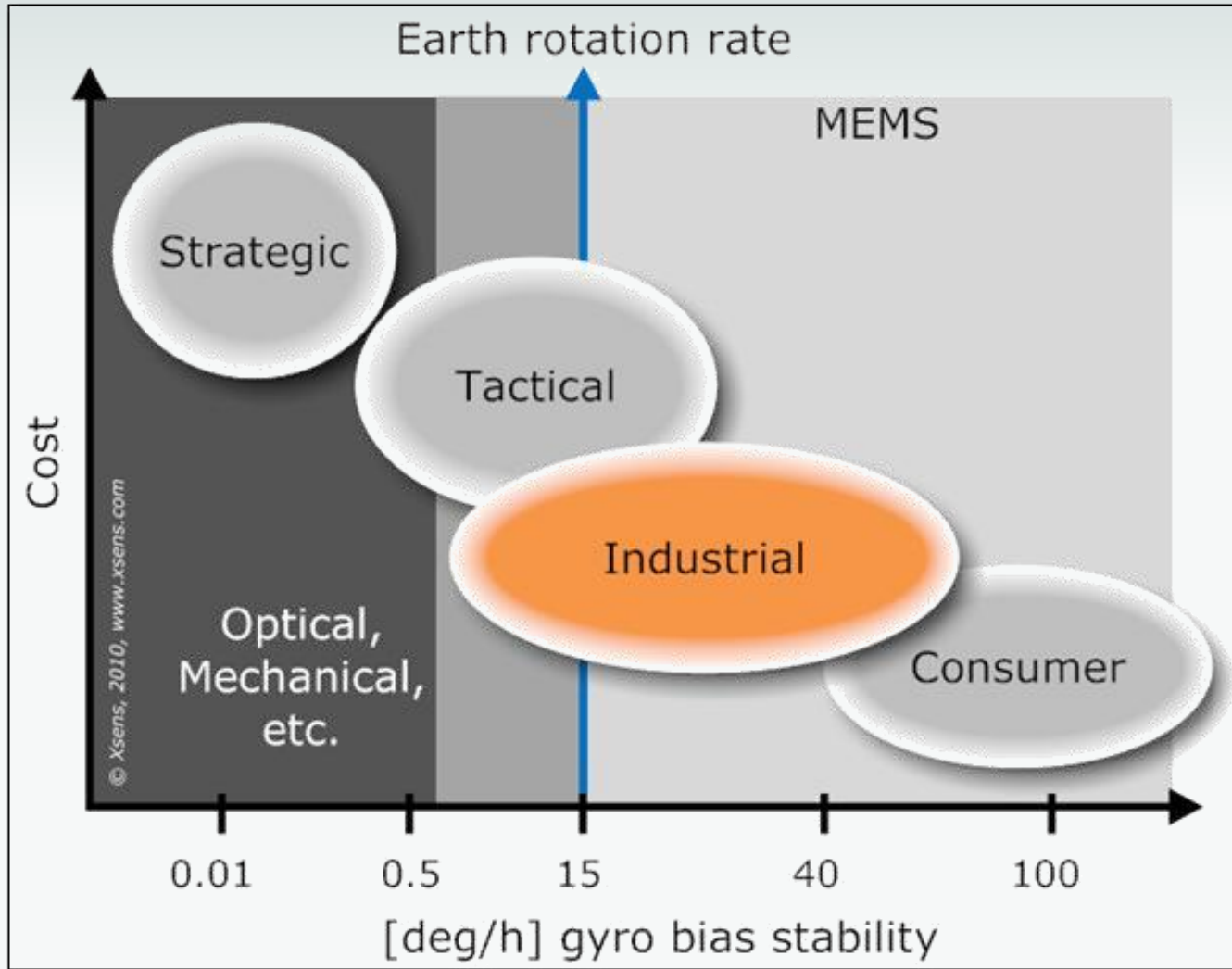




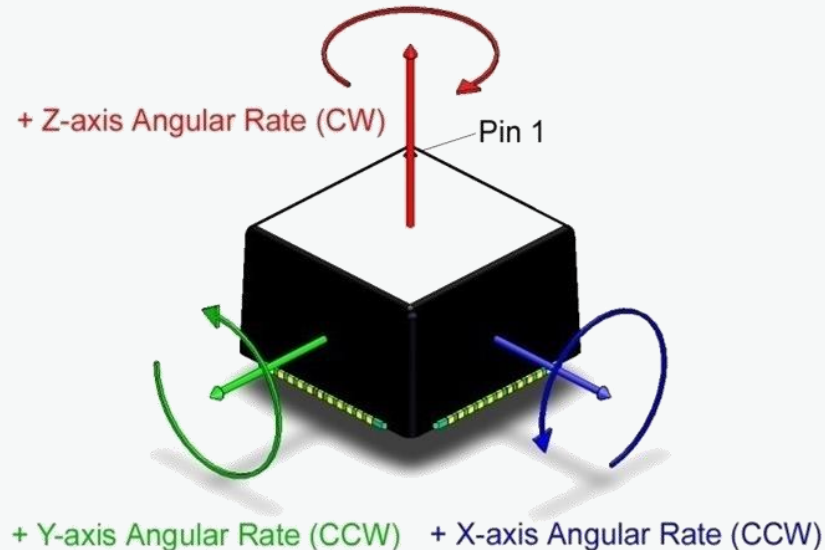
ACAMP Inertial Development

Sample Client Interactions



Example 1

- Client has a standalone, automotive grade gyroscope
- “Compare our gyroscope to the manufacturer data sheet”



Decide with Client on Test Requirements

Test Design

IMU Software Integration Design

IMU Hardware Integration Design

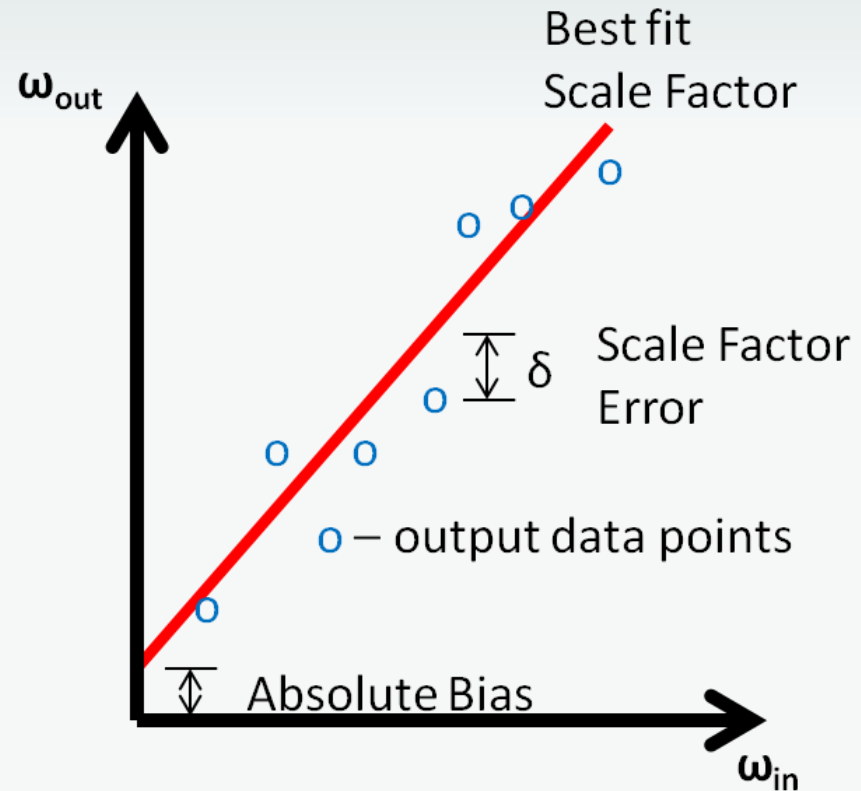
Test Integration

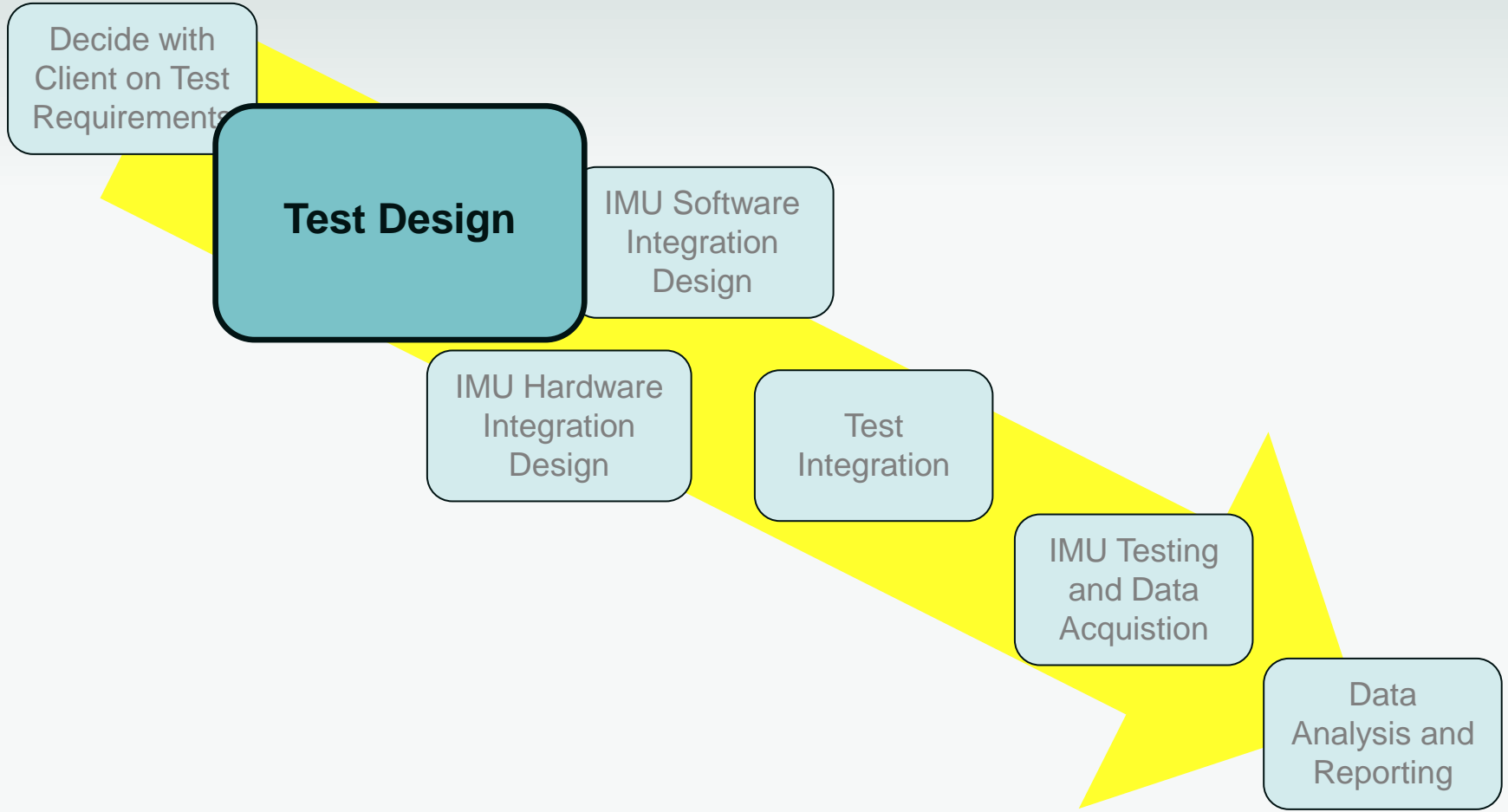
IMU Testing and Data Acquisition

Data Analysis and Reporting

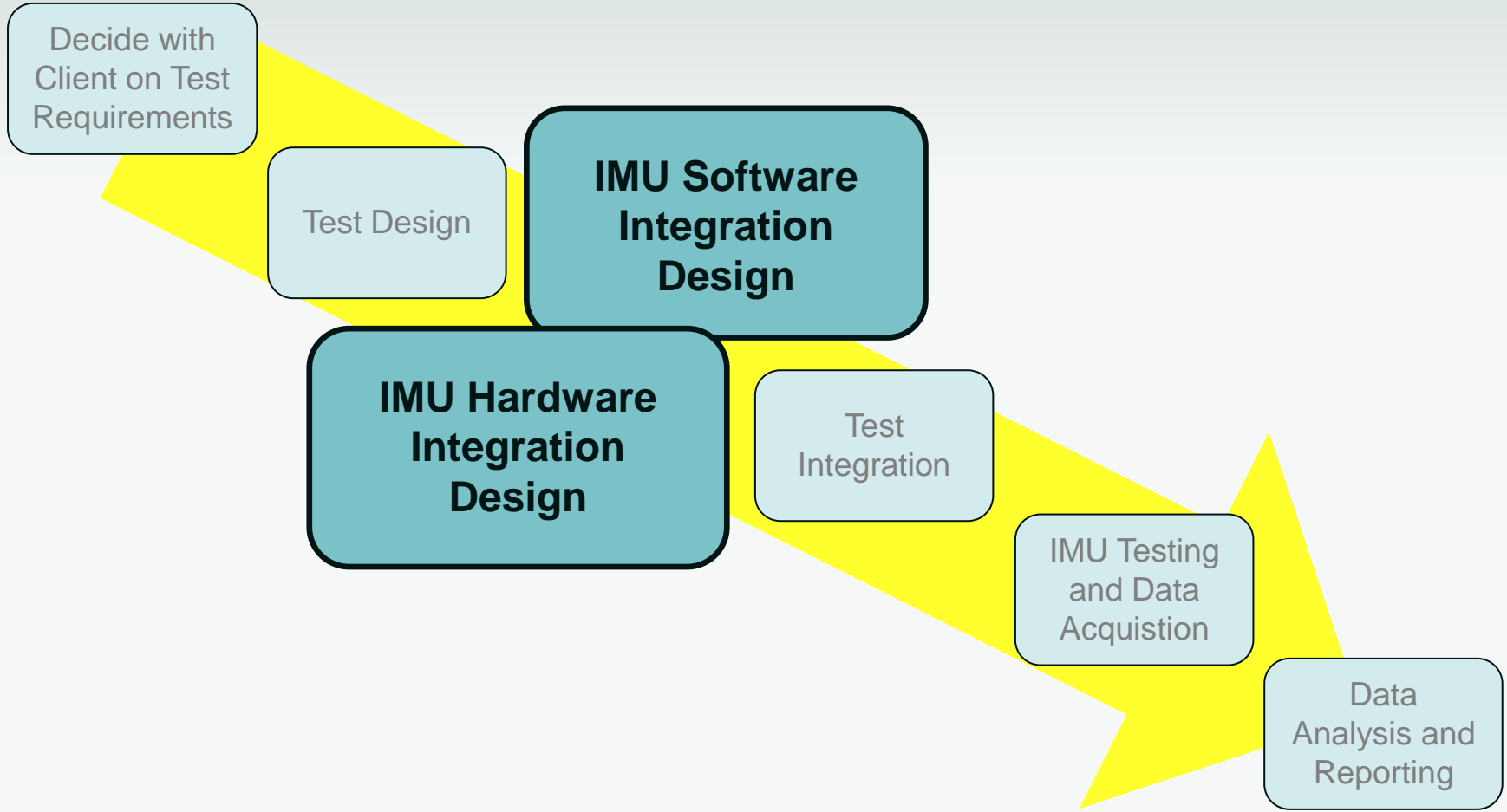
Client wants to know

- Scale factor
- Scale factor error
- Absolute bias





- Scale factor and scale factor error from rate test
- Test IMU at several rates between 0 and max RPM (positive and negative)
- Absolute bias \gg g -sensitivity \rightarrow can also be obtained by rate test

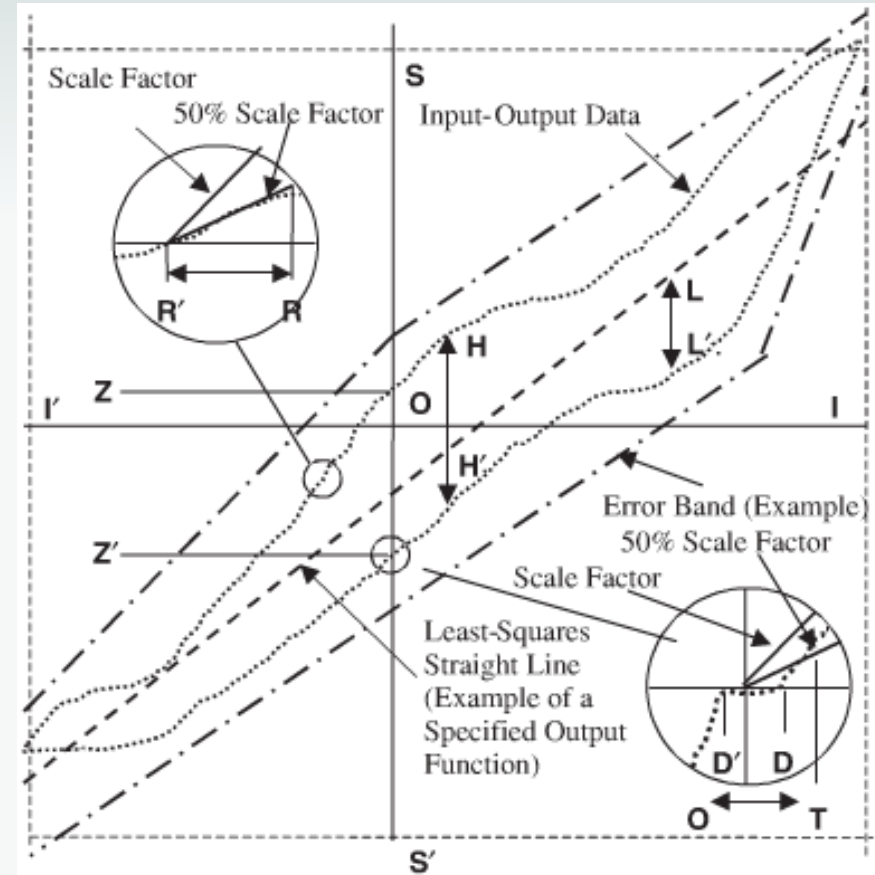


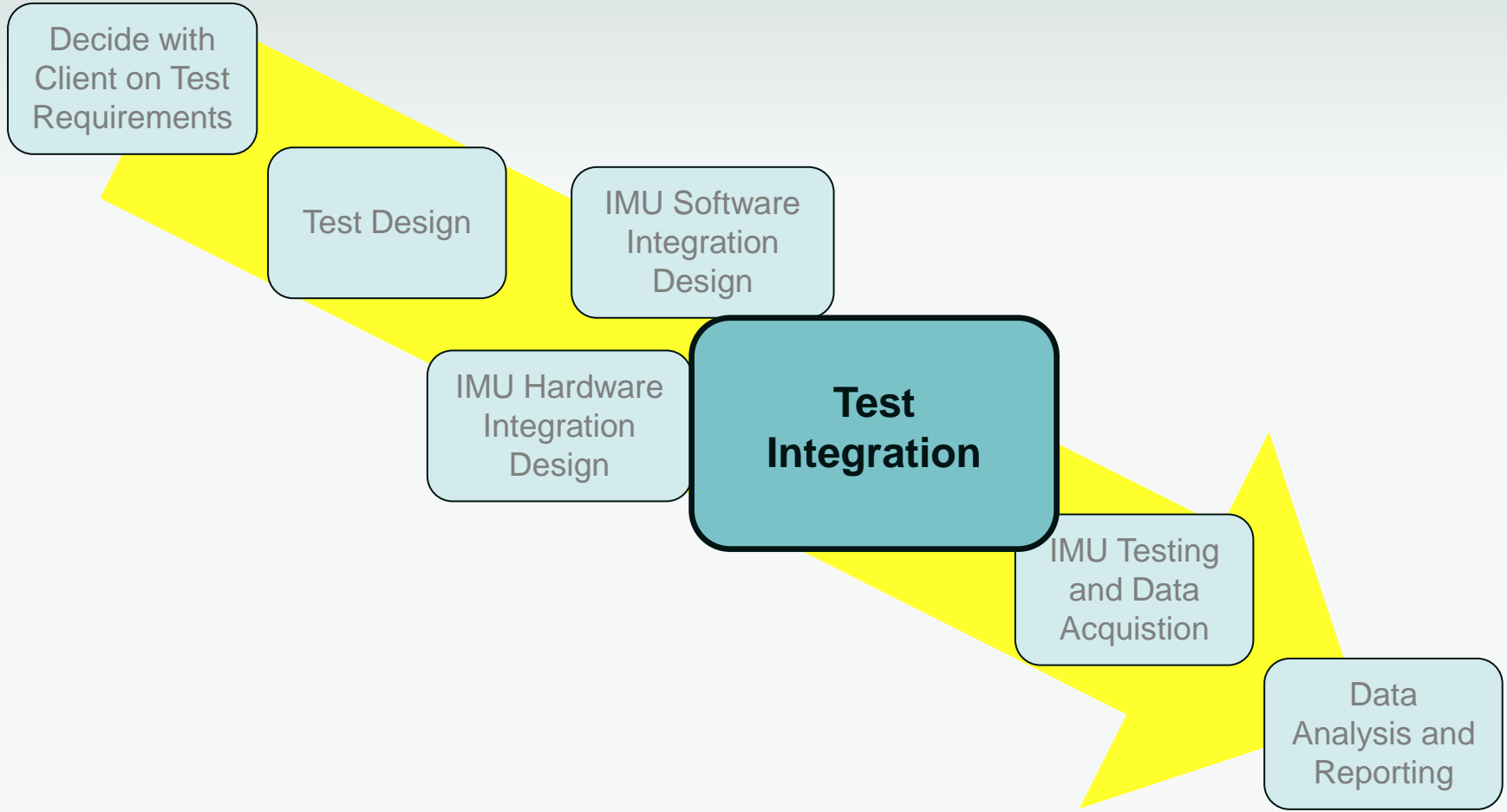
Software

- Tailor LabVIEW implemented SPI timing and settings

Hardware

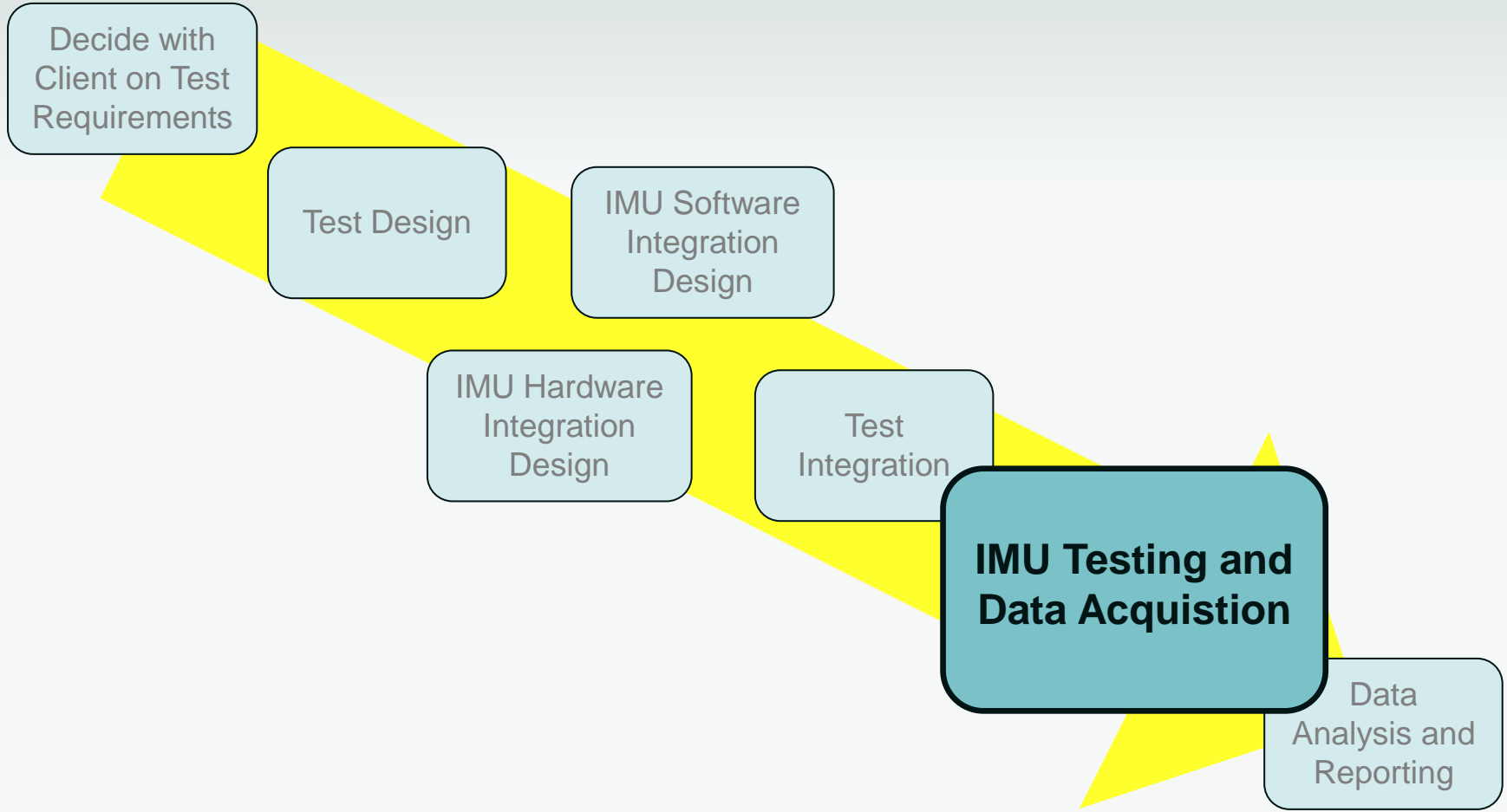
- Build cabling for IMU power and I/O
- Build mount for IMU stability



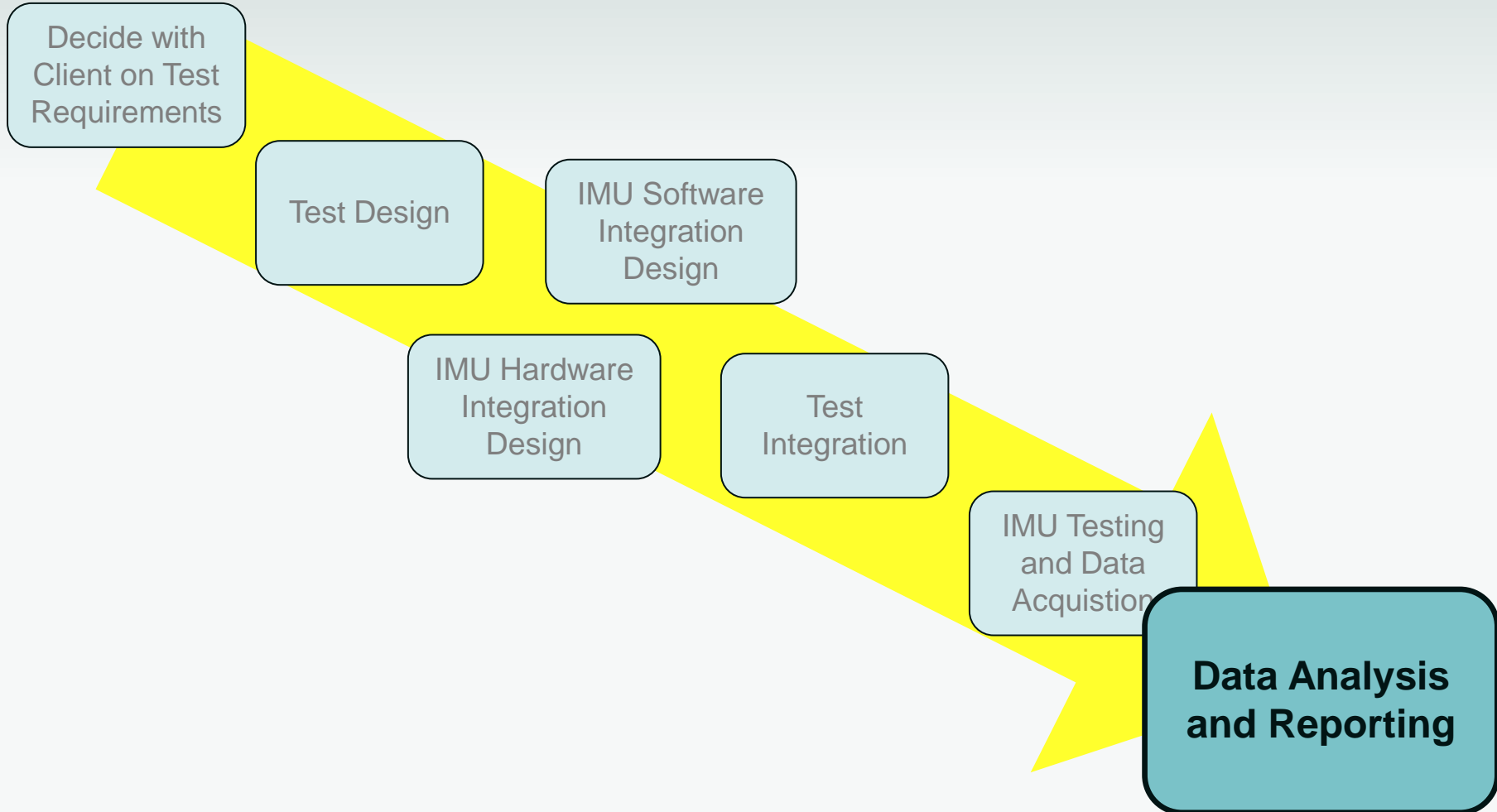


- ▣ Set testing steps to run on TestStand
 - ▣ Rate test – Timing chosen to minimize error based on in-run bias stability time
- ▣ Set TestStand variables
 - ▣ Thermal soak sufficient for gyro to stabilize
 - ▣ IMU capture rate – 200 Hz

Main (7)		
Latency Steps	Call DAQ + Motion Profile in <Current File>	
Rate Steps	Call DAQ + Motion Profile in <Current File>	
Latency Steps	Call DAQ + Motion Profile in <Current File>	Skip
Position Steps	Call DAQ + Motion Profile in <Current File>	Skip
Latency Steps	Call DAQ + Motion Profile in <Current File>	
Constant Acceleration Steps	Call DAQ + Motion Profile in <Current File>	Skip
Centrifuge Steps	Call DAQ + Motion Profile in <Current File>	Skip
<End Group>		



- Spin table at several rates
- Range : -160 RPM \rightarrow +160 RPM
 - Integral number of table revolutions at each rate for increased accuracy
 - Can alternate between positive and negative rates to mitigate any transient errors
 - Choose times at each rate to minimize noise error in measurement

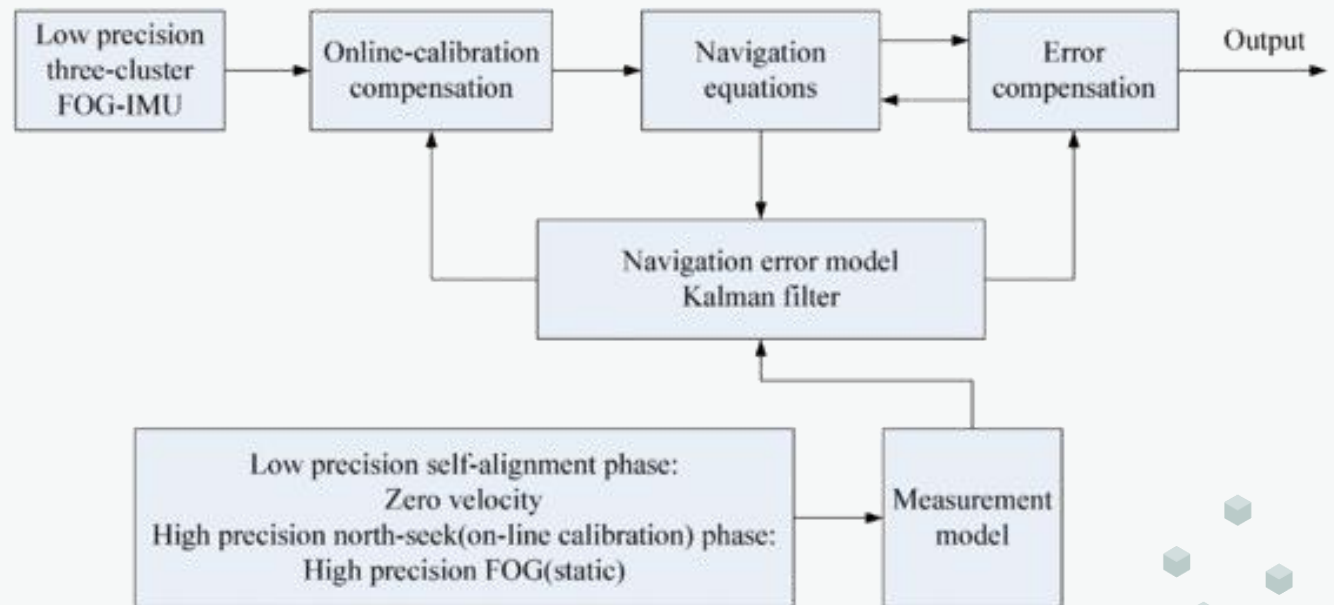


- Scale Factor - Extract linear least-squares line for 'Input Rate' vs. 'IMU Output'
- Scale Factor Error – Standard deviation of measured data from fit line
- Bias – y-intercept of fit line

ADIS 16375

Characteristic	ACAMP Measurement	Manufacturer Data Sheet
Scale Factor (Gyro)	0.013105 °/s/LSB	0.01311 °/s/LSB
Scale Factor Error (Gyro)	330 ppm	< 250 ppm
Absolute Bias (Gyro)	0.2 °/s	1 °/s (1 σ)

- Client has a tactical grade IMU integrated into their product, with additional software
- “Create a data sheet for our integrated IMU product”



Decide with Client on Test Requirements

Test Design

IMU Software Integration Design

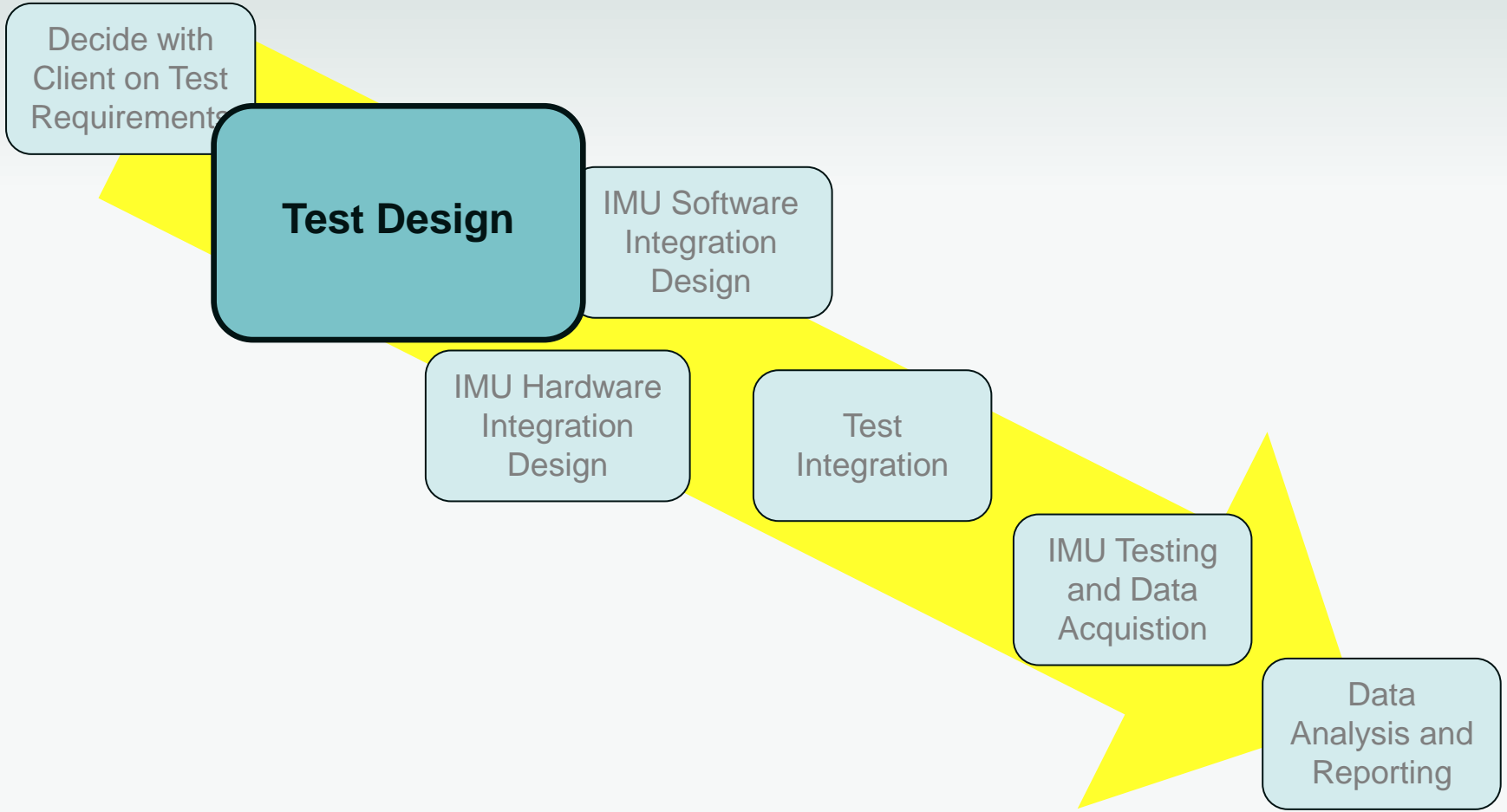
IMU Hardware Integration Design

Test Integration

IMU Testing and Data Acquisition

Data Analysis and Reporting

- Client wants to know
 - Gyro scale factor and scale factor error
 - Accl scale factor and scale factor error
 - Gyro and Accl bias
 - Gyro and Accl cross-axis misalignment
 - Noise – ARW and in-run bias stability, as function of temperature



Rate test

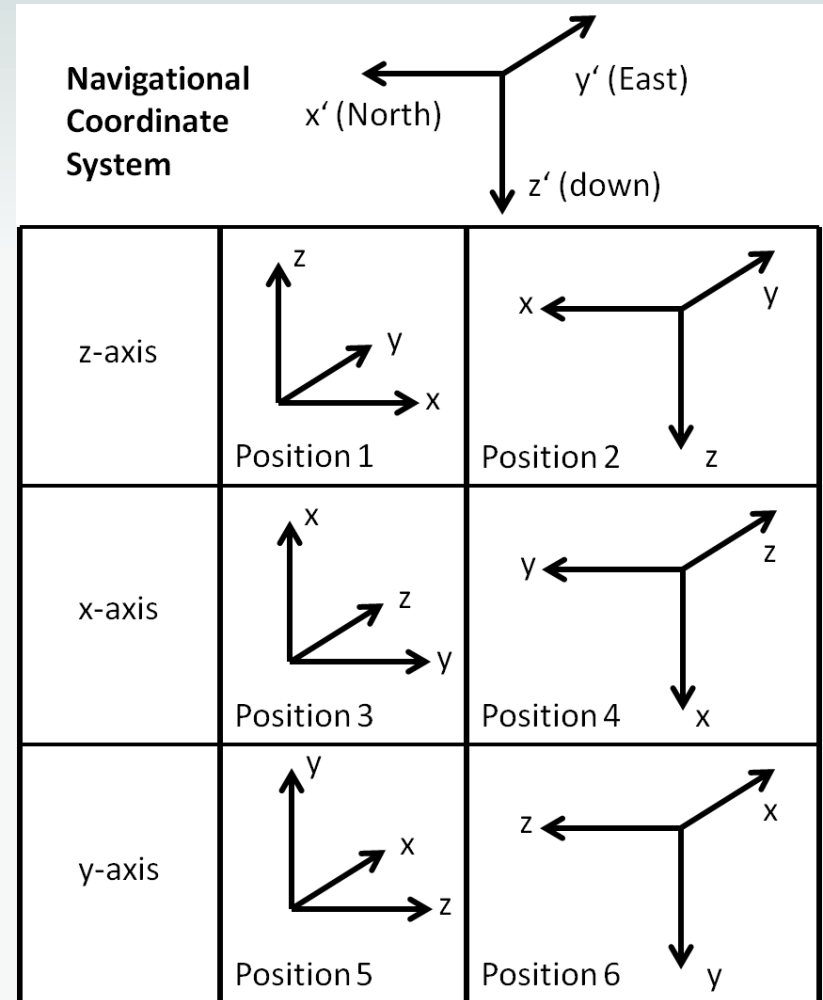
- Test across range of rates product is designed for

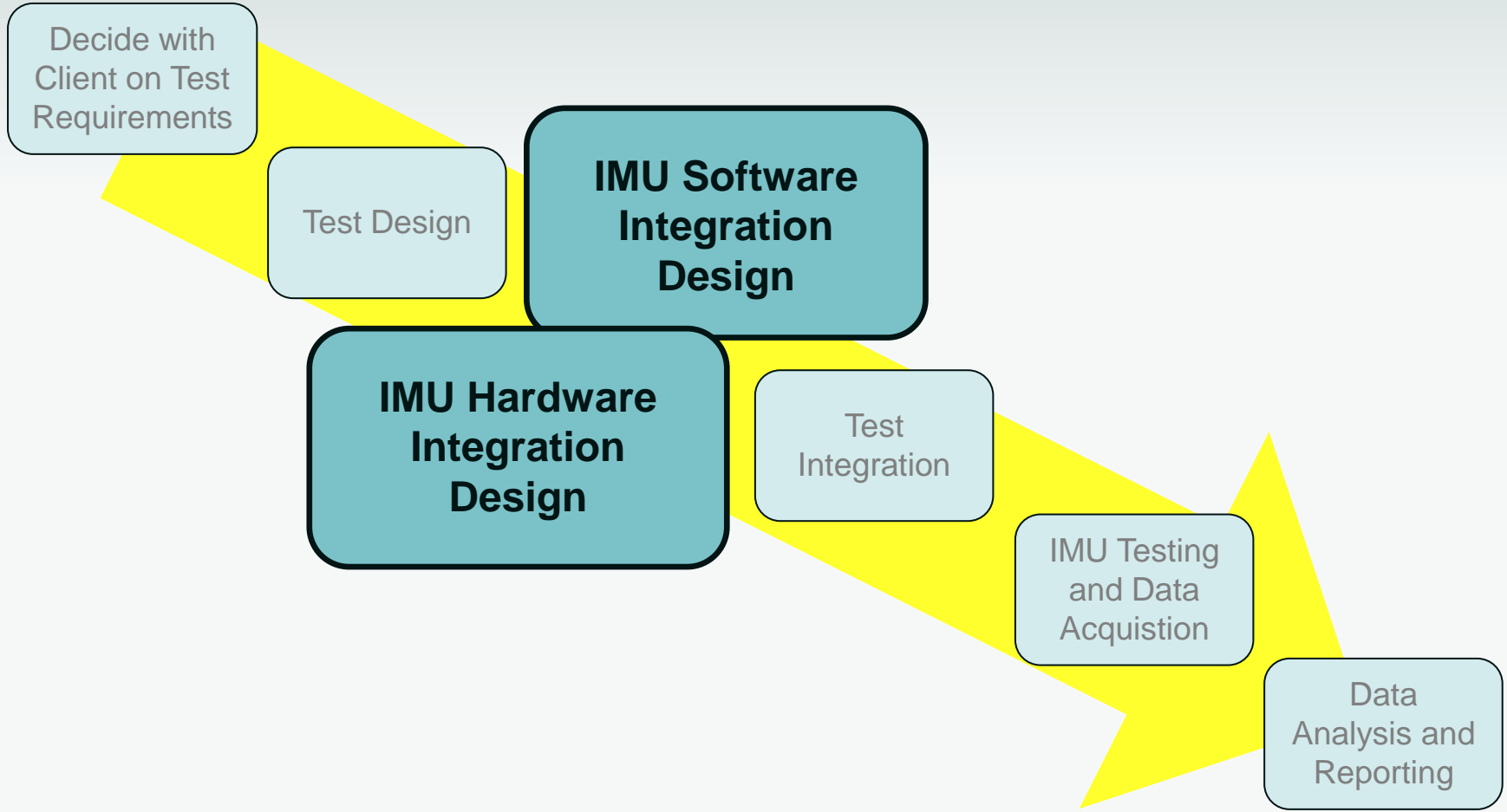
6-position test

- Positions should be held long enough to achieve accurate results

Allan Variance test

- Should be characterized long enough to achieve accurate results





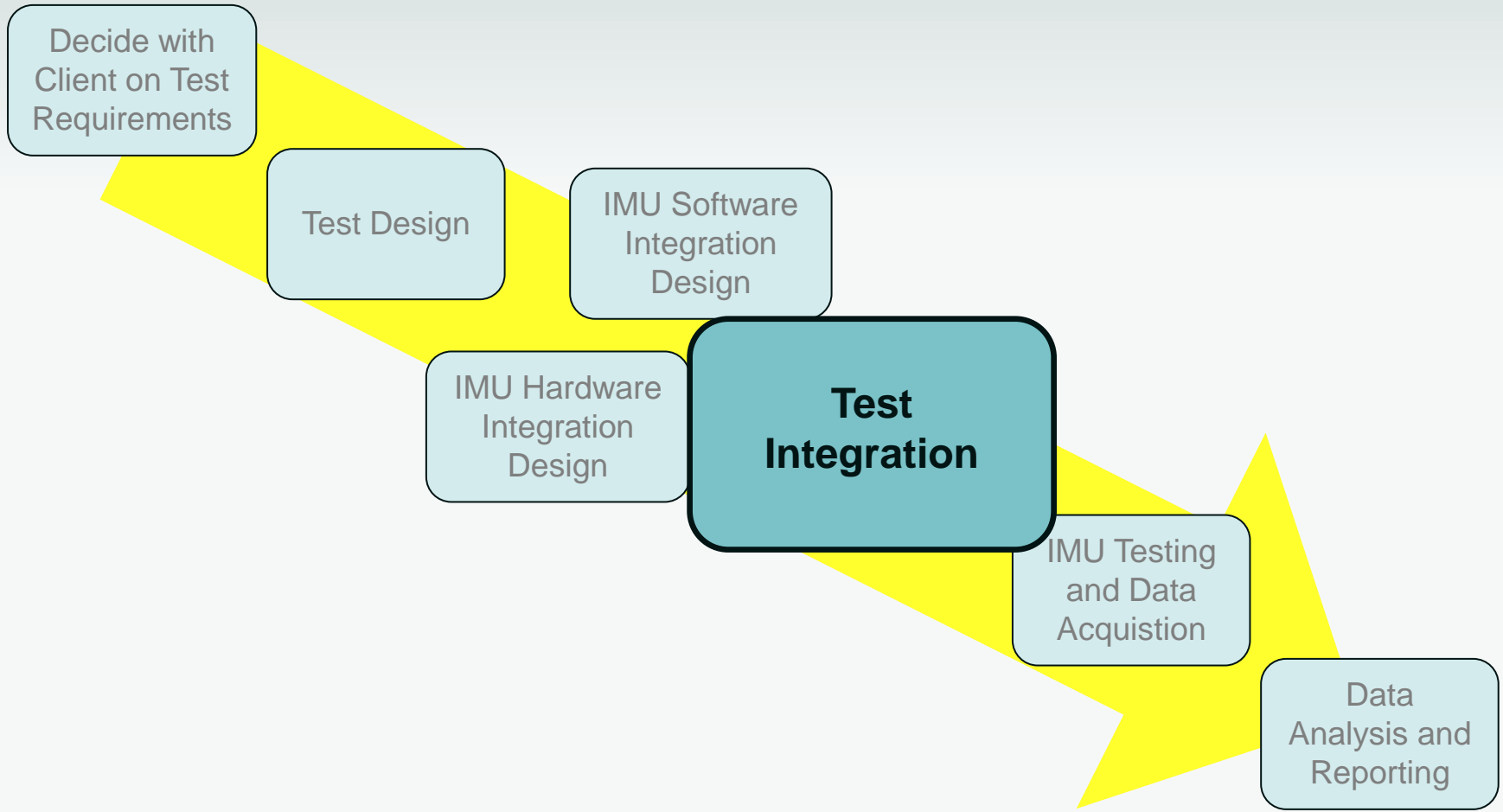
Software

- Client product has own data acquisition system
- Sync IMU product data to rate table data

Hardware

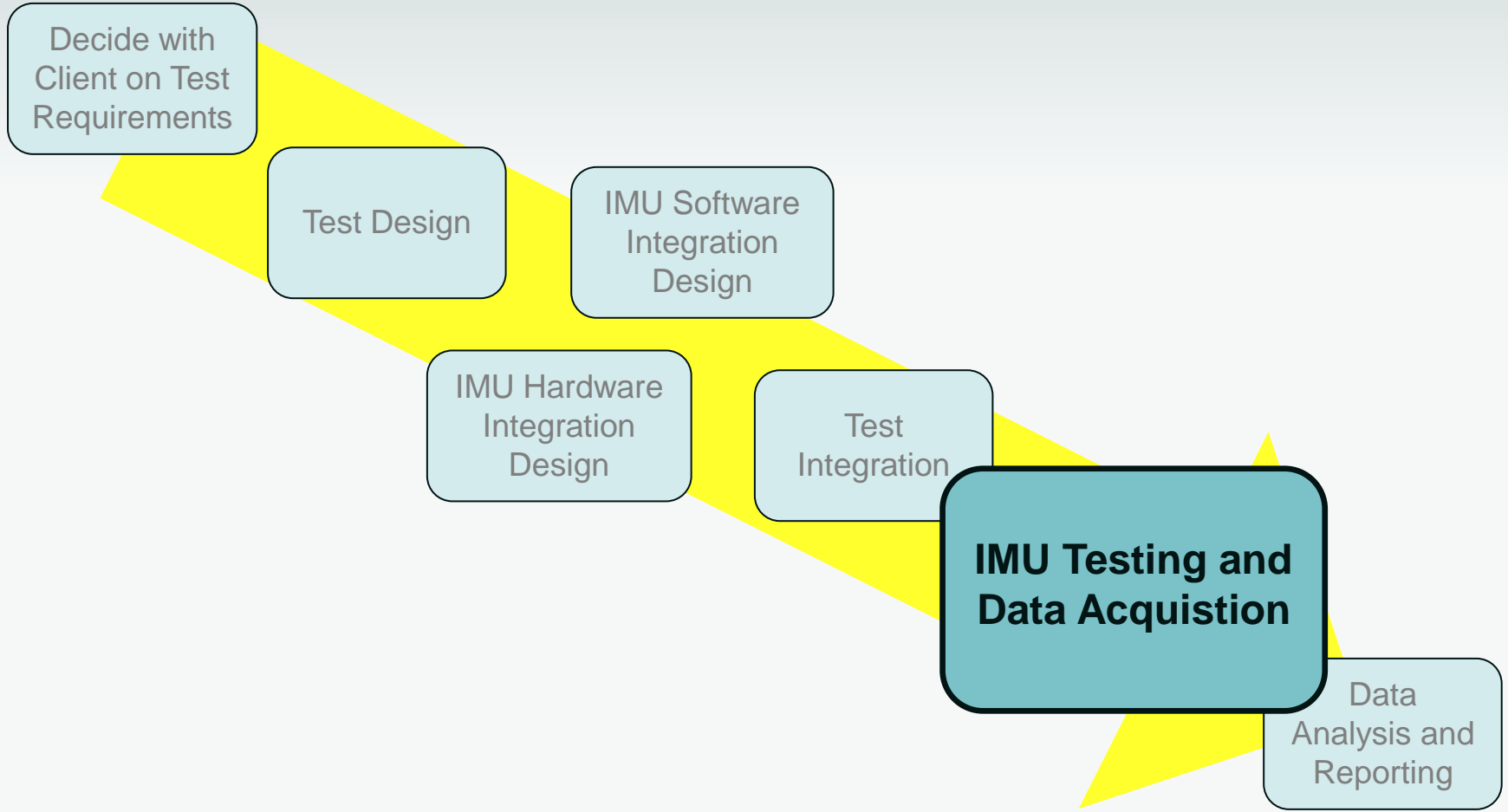
- Integrate cabling for device power and I/O
- Build mount for product stability



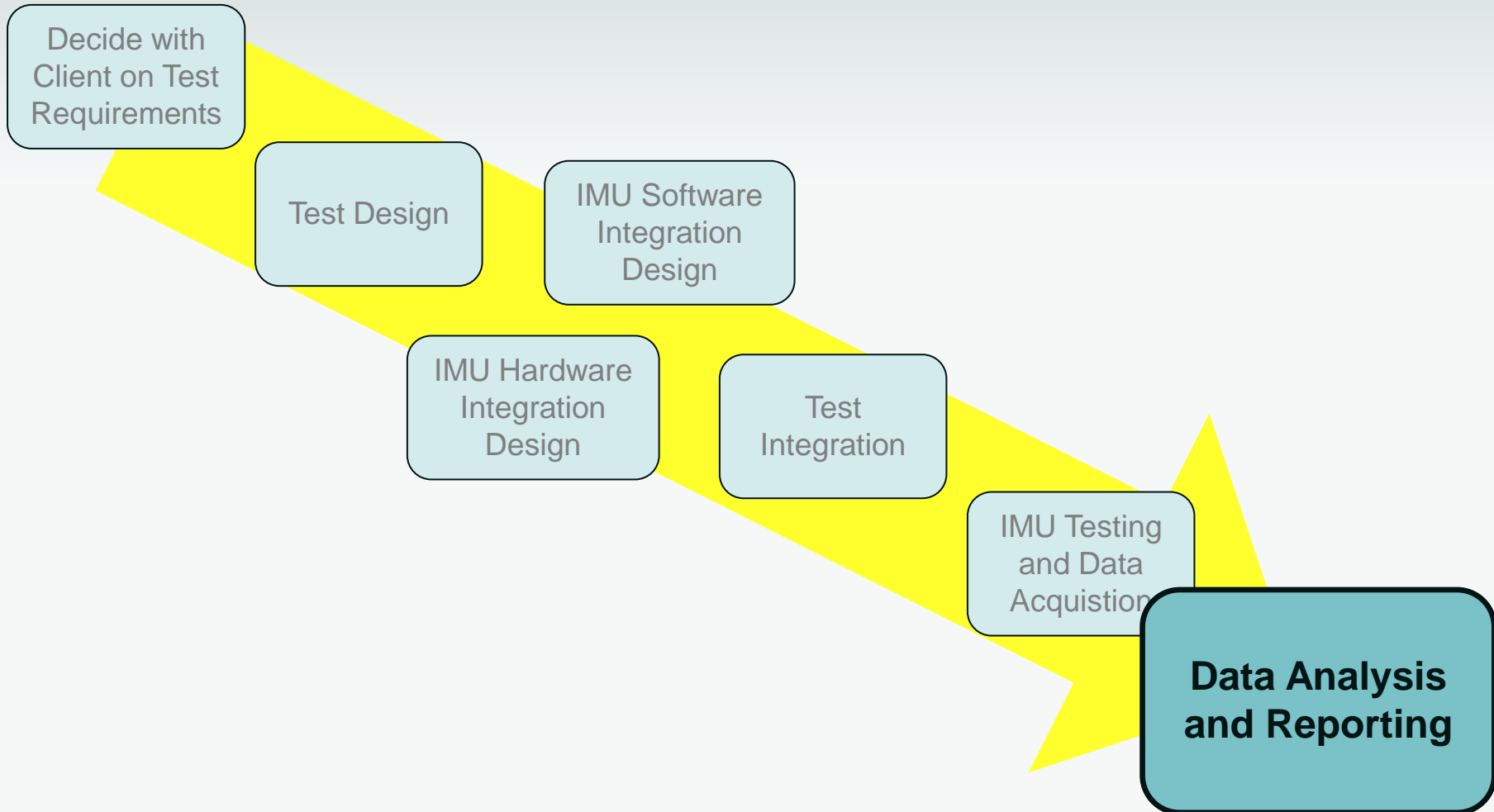


- ❖ Set testing steps to run on TestStand
 - ❖ Rate Test, 6-position test, Allan Variance test
 - ❖ Can be done in single or separate steps
- ❖ Set DAQ to collect rate table data only, add timing synchronization steps

Setup (7)			
f(x) Initialize Sequence Control Variables	FileGlobals.SkipSoak = FileGlobals.CancelledByUser = FileGlobals.AbortVI...		Done
f(x) Get Sequence Name	Locals.Tokens = Split(RunState.SequenceFile.Path, "\\")		Done
f(x) Set DAQ command to Connect	FileGlobals.DAQ_Command = 0		Done
Initialize Instruments	Call Initialize Instruments in <Current File>	Post Action	Passed
IdentifyUUT	Action, DisplayUUTInformationDialog (modelsupport2.dll)	Precondition, Post Expression, Post Action	Done
Turn Torquers on	Action, ACAMP - Host PC.Ivproj, Aero4000 - Enable Torquers.vi		Done
Run cRIO Host Interface	Call 'My Computer\ADIS - Host Main.vi' Asynchronously on Host 'localhost...	New Thread	Done
<End Group>			
Main (7)			
For	{0} Locals.Index=StationGlobals.RunState.TestStep; Locals.Index< GetNu...		Done
f(x) Update Thermal Controller Variables	Locals.ThermalChamberParameters.Temp_Set_Point = FileGlobals.TempSt...		Done
f(x) Save Test Step	StationGlobals.RunState.TestStep = Locals.Index, RunState.Engine.Com...		Done
Start Thermal Ramp and Soak	Call 'My Computer\Thermal Chamber - Main.vi' Asynchronously on Host 'd...	Post Action, New Thread	Done
Status Monitor	Action, ACAMP - Host PC.Ivproj, Status Monitor.vi	Post Expression, Post Action	
Test Profile	Call Test Profile in <Current File>		
End			
<End Group>			



- ❖ Rate test - Spin table through range of rates, along all 3 gyro axes
- ❖ 6-Position test – Orient table in 6 orthogonal positions
- ❖ Allan Variance Test – Collect static data, temperature controlled



- ❖ Gyro scale factor – same as example 1
- ❖ Accl scale factor – 2 g difference between vertically up and down orientation
- ❖ Bias – average output of 6 orthogonal positions has 0 net external bias
- ❖ Noise – Allan Variance plot can be derived as difference of average between successive time intervals

RATE TABLE DEMO

